ZSOLT LANGI, University of Calgary, 2500 University Dr. NW, Calgary, AB T2N 1V4 Ball-polytopes and 1-convexity

For points $p, q \in \mathbb{R}^n$, $[p,q]_1$ denotes the intersection of all the unit balls that contain p and q. A set of diameter at most two is called 1-convex if, for any pair p, q of its points, it contains $[p,q]_1$. The intersection of finitely many unit balls is called a ball-polytope. In this talk we examine which properties of convex sets and convex polytopes can be translated to the language of 1-convex sets and ball-polytopes.

This is joint work with K. Bezdek, M. Naszodi and P. Papez.